

FIG. 1

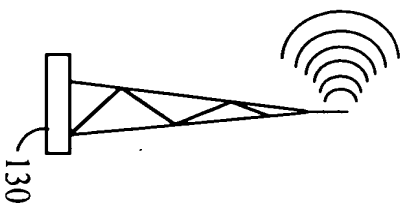
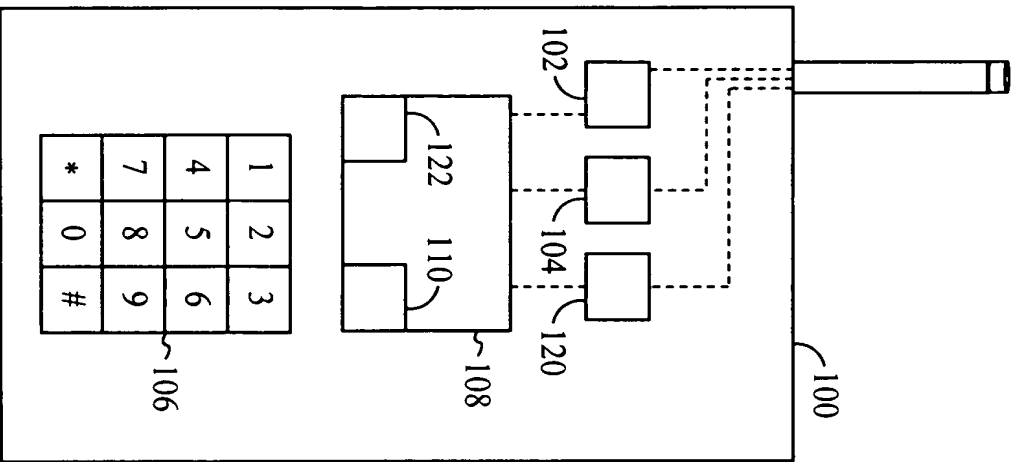


FIG. 2

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POSITION LOCATION RANGE VALUES	MATCHING SID(S) INDEX
L1	S1, S2
L2	S1
L3	S20,S21,S30
L4	S32
L5	S40,S45,S46
L6	S3,S4
...	...
...	...
...	...
...	...

CO-
ORDINATES
CONVERTER

FIG. 3

300 ↗

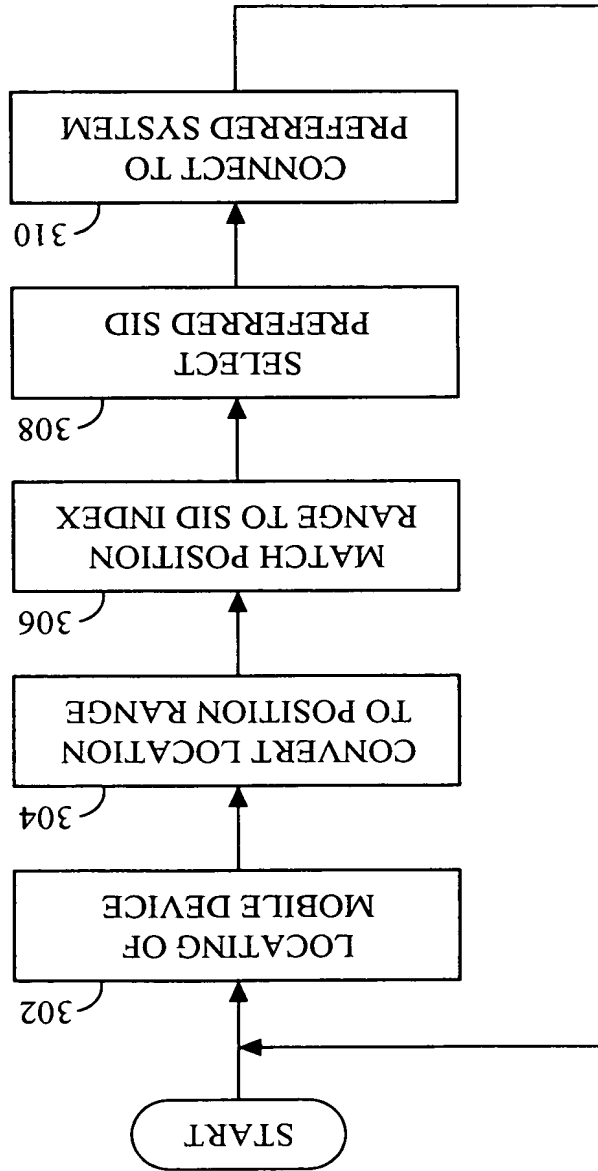


FIG. 4